

Type theory and concurrency: directed homotopy type theory

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17 March 2018

Goal

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To develop a logic for directed homotopy theory

- ▶ To prove theorems about concurrent processes

Homotopy type theory

HoTT

A logic for homotopy theory.

Basic objects of the language

Dependent types:

$$b : B \vdash E(b) \text{ TYPE} \quad \rightsquigarrow \quad \begin{array}{c} E \\ \downarrow \text{fibration } \pi \\ B \end{array}$$

Dependent terms:

$$b : B \vdash e(b) : E(b) \quad \rightsquigarrow \quad \text{section } e \begin{array}{c} E \\ \uparrow \downarrow \text{fibration } \pi \\ B \end{array}$$

Homotopy type theory

Type formers

Usually postulate that certain types can be formed:
e.g., from $b : B \vdash E(b)$ and $b : B \vdash F(b)$ can form

- ▶ the coproduct $b : B \vdash E(b) + F(b)$,
- ▶ the hom-type $b : B \vdash E(b) \rightarrow F(b)$.

As in category theory: we postulate that objects with certain universal properties exist.

The surprising type former

The identity type

Equality is defined in this language by a universal property:

- ▶ For $b : B \vdash E(b)$, we define a new type $b : B \vdash \text{Id}_b(E)$ to be the *smallest reflexive relation* on E .

$$b : B \vdash \epsilon_0 \times \epsilon_1 : \text{Id}_b(E) \rightarrow E(b) \times E(b)$$

$$b : B \vdash r(b) : E(b) \rightarrow \text{Id}_b(E)$$

- ▶ We think of terms $b : B \vdash p(b) : \text{Id}_b(E)$ as being an equality $\epsilon_0(pb) = \epsilon_1(pb)$

This makes equality *weaker* than usual set-theoretic equality.

- ▶ Easier for a computer to handle.
- ▶ The definition says that $\text{Id}_b(E)$ is a (very good) path object:

$$E(b) \xrightarrow[\text{acof}]{r} \text{Id}_b(E) \xrightarrow[\text{fib}]{\epsilon_0 \times \epsilon_1} E(b) \times E(b)$$

Why HoTT?

- ▶ It's a logic for homotopy theory.

Theorem (N)

Let \mathcal{C} be a finitely complete category.

The category of models¹ of type theory with Id types in \mathcal{C} is equivalent to the category of weak factorization systems $(\mathcal{L}, \mathcal{R})$ on \mathcal{C} where

1. every map to the terminal object is in \mathcal{R} and
2. \mathcal{L} is stable under pullback along \mathcal{R} .

¹display map categories

Why HoTT?

- ▶ It's a logic for homotopy theory.
- ▶ Which can be used for formal verification on a computer.

Example: reversing paths

Thm: Paths are reversible.

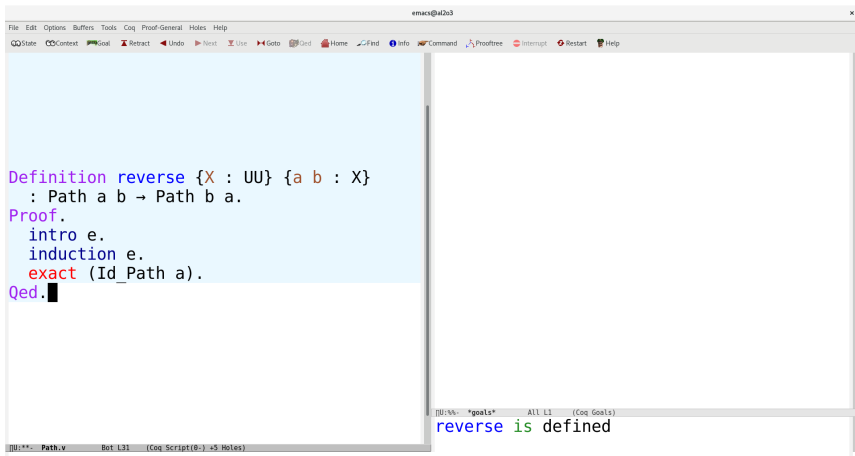
A categorical proof: Given a very good path object

$$X \xrightarrow[\text{acof}]{r} \text{Path}(X) \xrightarrow[\text{fib}]{\epsilon_0 \times \epsilon_1} X \times X,$$

we get a solution to the following lifting problem.

$$\begin{array}{ccc} X & \xrightarrow{r} & \text{Path}(X) \\ \downarrow r & \nearrow & \downarrow \epsilon_0 \times \epsilon_1 \\ \text{Path}(X) & \xrightarrow{\epsilon_1 \times \epsilon_0} & X \times X \end{array}$$

A type theoretic proof in the computer:



The image shows a screenshot of an Emacs editor window titled "emacs@42e3". The window contains a Coq proof script. The script defines a function "reverse" that takes a type X and two elements a and b of type X , and returns a path from a to b . The proof is completed with "Qed".

```
Definition reverse {X : UU} {a b : X}
  : Path a b → Path b a.
Proof.
  intro e.
  induction e.
  exact (Id_Path a).
Qed.█
```

At the bottom right of the window, a status bar shows the current goal: "reverse is defined".

Why HoTT?

- ▶ It's a logic for homotopy theory.
- ▶ Which can be used for formal verification on a computer.
- ▶ Everything is invariant under homotopy:
for every $b : B \vdash E(b)$, for every $a, b : B$, there is a function

$$\text{transport} : E(a) \times \text{Id}(a, b) \rightarrow E(b).$$

Example: contractibility

Given $b : B \vdash E(b)$, define $b : B \vdash \text{isContr}(Eb)$ (type of contractions of Eb).

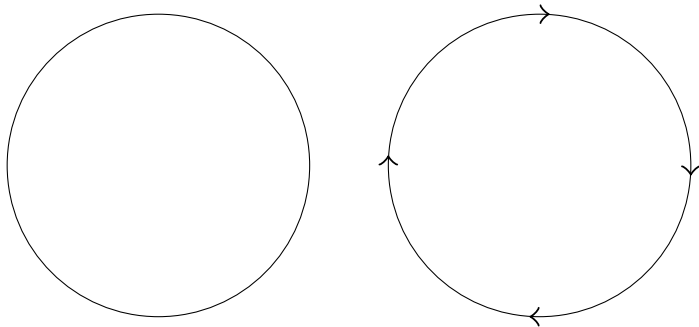
If there is a contraction $c : \text{isContr}(Ea)$ and a path $p : \text{Id}(a, b)$, then there is a contraction $\text{transport}(c, p) : \text{isContr}(Eb)$.

Even true for $T : \text{TYPE} \vdash \text{isContr}(T)$.

Directed spaces

Rough definition

A directed space is a space together with a subset of its paths which are marked as *directed*.



Directed spaces and concurrency

Concurrent processes can be represented by directed spaces.

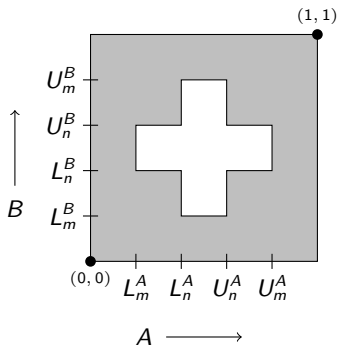


Figure: The Swiss flag

Fundamental question:

Which states are safe? Which states are reachable?

Design criteria for directed HoTT

- ▶ A logic for directed homotopy theory
 - ▶ Same underlying syntax as HoTT
 - ▶ With a new type former $\text{hom}(-)$ whose terms represent directed paths
- ▶ Which can be used for formal verification on a computer.
- ▶ Where everything is covariant with directed homotopy:
for every $b : B \vdash E(b)$, for every $a, b : B$, there is a function

$$\text{transport} : E(a) \times \text{hom}(a, b) \rightarrow E(b).$$

Example: reachability

Given $* \vdash D$, define $d : D \vdash \text{Reach}(d)$ (type of ways to reach d from the initial point).

If there is a $r : \text{Reach}(d)$ and a directed path $p : \text{hom}(d, e)$, then there is a $\text{transport}(r, p) : \text{Reach}(e)$.

Rules for directed HoTT

$$\frac{\Gamma \vdash T : \mathcal{U}}{\Gamma \vdash T^{\text{core}} : \mathcal{U}} \quad \frac{\Gamma \vdash T : \mathcal{U}}{\Gamma \vdash T^{\text{op}} : \mathcal{U}} \quad \frac{\Gamma \vdash T : \mathcal{U} \quad \Gamma \vdash t : T^{\text{core}}}{\Gamma \vdash \iota t : T} \quad \frac{\Gamma \vdash T : \mathcal{U} \quad \Gamma \vdash t : T^{\text{core}}}{\Gamma \vdash \iota^{\text{op}} t : T^{\text{op}}}$$

$$\frac{\Gamma \vdash T : \mathcal{U} \quad \Gamma \vdash s : T^{\text{op}} \quad \Gamma \vdash t : T}{\Gamma \vdash \text{hom}_T(s, t) : \mathcal{U}} \quad \frac{\Gamma \vdash T : \mathcal{U} \quad \Gamma \vdash t : T^{\text{core}}}{\Gamma \vdash 1_t : \text{hom}_T(\iota^{\text{op}} t, \iota t) : \mathcal{U}}$$

$$\frac{\Gamma \vdash T : \mathcal{U} \quad \Gamma, s : T^{\text{core}}, t : T, f : \text{hom}_T(\iota^{\text{op}} s, t) \vdash D(f) : \mathcal{U} \quad \Gamma, s : T^{\text{core}} \vdash d(s) : D(1_s)}{\Gamma, s : T^{\text{core}}, t : T, f : \text{hom}_T(\iota^{\text{op}} s, t) \vdash \delta_r(d, f) : D(f)}$$

$$\frac{\Gamma \vdash T : \mathcal{U} \quad \Gamma, s : T^{\text{op}}, t : T^{\text{core}}, f : \text{hom}_T(s, \iota t) \vdash D(f) : \mathcal{U} \quad \Gamma, s : T^{\text{core}} \vdash d(s) : D(1_s)}{\Gamma, s : T^{\text{op}}, t : T^{\text{core}}, f : \text{hom}_T(s, \iota t) \vdash \delta_\ell(d, f) : D(f)}$$

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A model in categories

- There is a weak factorization system $(\mathcal{L}, \mathcal{R})$ in Cat enrichedly cofibrantly generated by the inclusion of the domain into a morphism.

$$0 \hookrightarrow (0 \rightarrow 1)$$

- The usual functor $\text{hom} : \mathcal{C}^{\text{op}} \times \mathcal{C} \rightarrow \text{Set}$ becomes a Grothendieck opfibration $\pi : \text{hom}(\mathcal{C}) \rightarrow \mathcal{C}^{\text{op}} \times \mathcal{C}$, which is in \mathcal{R} .
- There is a functor $\text{ob}\mathcal{C} \rightarrow \text{hom}^=(\mathcal{C})$ which is in \mathcal{L} .

$$\begin{array}{ccccc}
 \text{ob}\mathcal{C} & \overset{\curvearrowright}{\dashrightarrow} & \text{hom}^=(\mathcal{C}) & \longrightarrow & \text{hom}(\mathcal{C}) \\
 & \searrow & \downarrow & \lrcorner & \downarrow \pi \\
 & & (\text{ob}\mathcal{C}) \times \mathcal{C} & \longrightarrow & \mathcal{C}^{\text{op}} \times \mathcal{C}
 \end{array}$$

- The rules above axiomatize the lifting property that these maps (and other maps of the wfs) have against each other.

Summary & future work

Summary

We have:

- ▶ a type theory for directed paths
- ▶ with a model in *Cat*.

Summary

We need:

- ▶ to integrate this into old HoTT (i.e. have Id and hom in the same theory);
- ▶ to find a model in a category of directed spaces;
- ▶ to find models in all categories of directed spaces.

Thank you!